



Geometric Modeling

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Discrete Mathematics

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Unit materials



- Lecture notes
 - Seminar handouts
- are available at

<http://gm.softalliance.net/>

Advice: download and print lecture notes
before the next lecture



Example: k-D unit cube

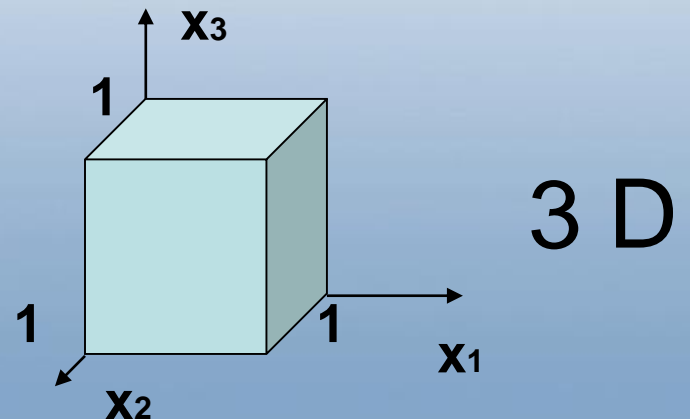
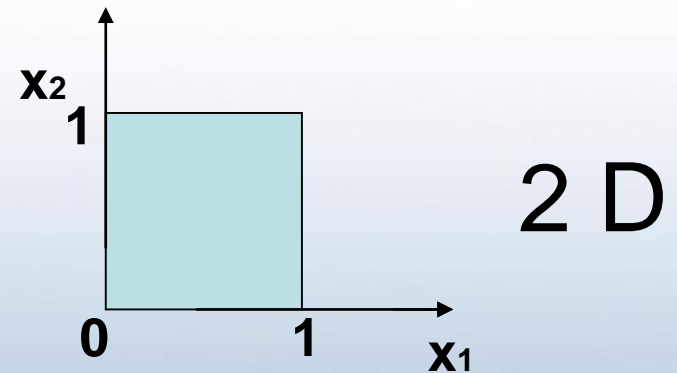
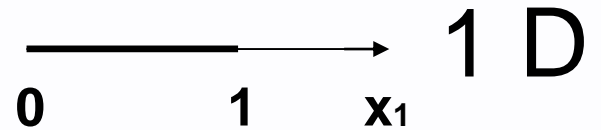
A unit cube in k-D space is a set of points $P(x_1, x_2, \dots, x_n)$ such as:

$$0 \leq x_1 \leq 1$$

$$0 \leq x_2 \leq 1$$

...

$$0 \leq x_n \leq 1$$





Shape Dimension

A shape is k -dimensional if there is a continuous one-to-one mapping of the k -dimensional cube (ball) to this shape.

$k \leq n, n = 1 - 4$	<i>Shape</i>
0	Point
1	Curve
2	Surface
3	Solid
$k = 3, n = 4$	Volume



Defining a Point Set

- List of points
- Mapping of a known set
- Point membership rule
- Generation rule



List of Points

2D space

$\langle X_1, Y_1 \rangle$

$\langle X_2, Y_2 \rangle$

...

$\langle X_k, Y_k \rangle$

3D space

$\langle X_1, Y_1, Z_1 \rangle$

$\langle X_2, Y_2, Z_2 \rangle$

...

$\langle X_k, Y_k, Z_k \rangle$

nD space

$\langle X_{11}, X_{12}, X_{13}, \dots, X_{1n} \rangle$

$\langle X_{21}, X_{22}, X_{23}, \dots, X_{2n} \rangle$

...

$\langle X_{k1}, X_{k2}, X_{k3}, \dots, X_{kn} \rangle$

Model: Linear array defines one point in nD space

Only finite point sets can be defined in this way and no continuous shape (such as curve or surface) can be defined.



Scanned point cloud

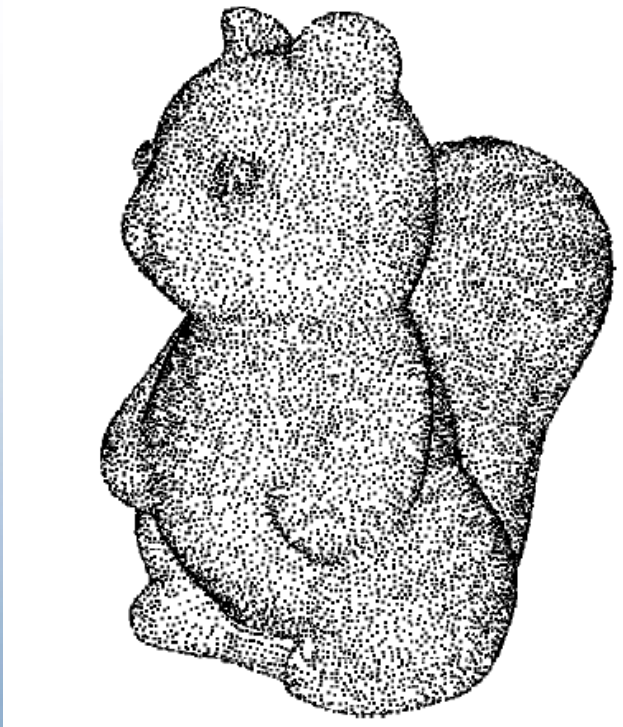
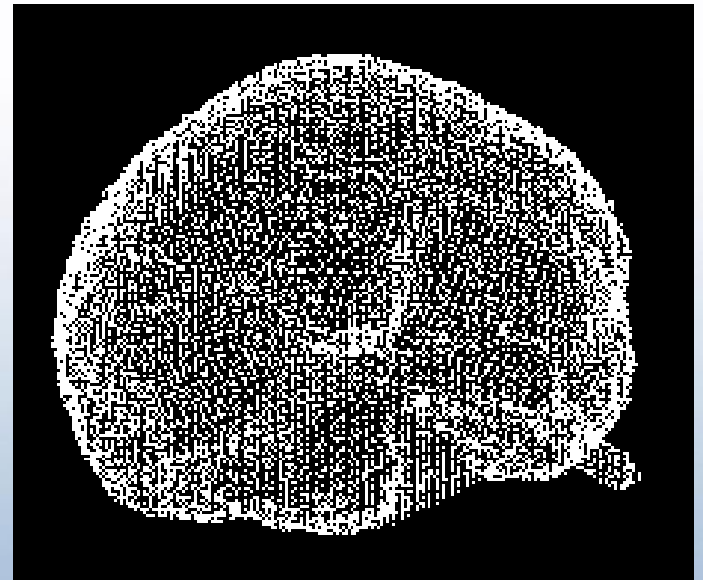


Image by Yu. Otake and A. Belyaev



Point Cloud of a Human Brain

http://www.fpsols.com/point_cloud.html



Examples of Particle systems



Stormy sea



Animation by Steve Green
DreamScape plug-in to 3DS MAX



Explosion

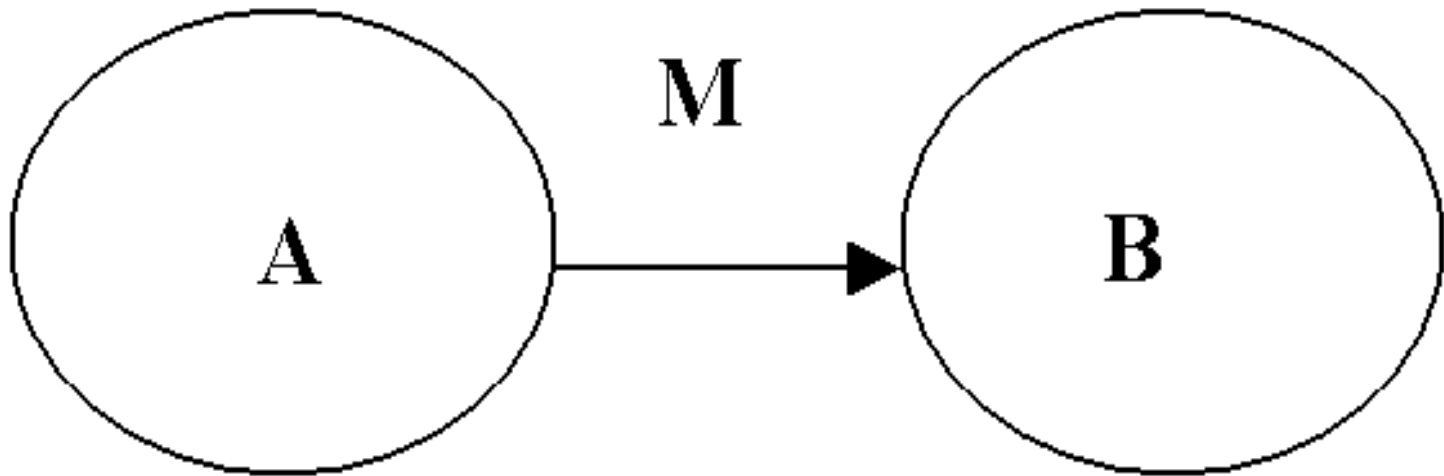


Animation by Thomas Marque
DreamScape plug-in to 3DS MAX



Mapping of a Known Set

$$M : A \rightarrow B$$



Parametric curves, surfaces and volumes are defined in this way.



“Explicit” Curve in 2D

Mapping

$$F: \mathbb{R} \rightarrow \mathbb{R}$$

Definition:

$$y = f(x)$$

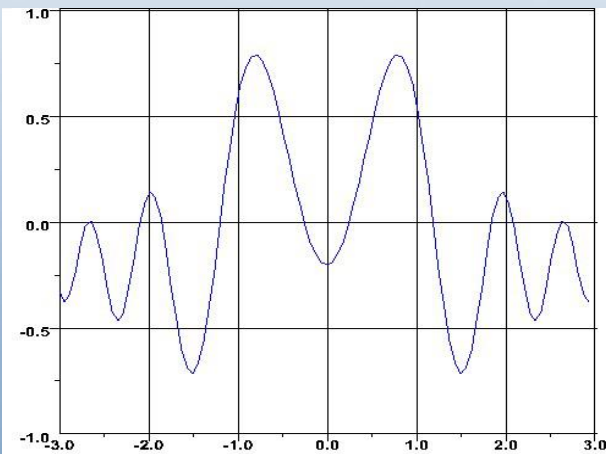


Image from HyperFun

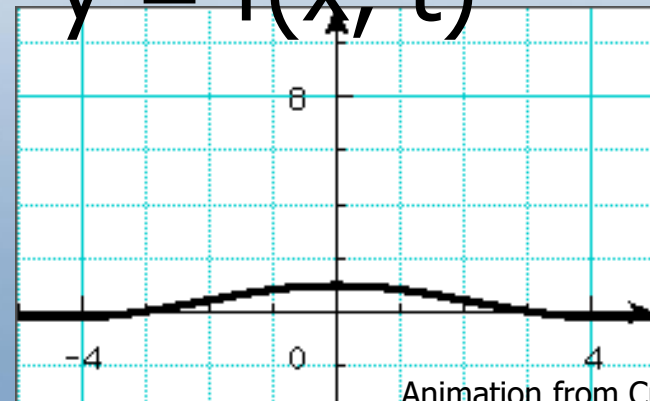
+ time t

Mapping

$$F: \mathbb{R}^2 \rightarrow \mathbb{R}$$

Definition:

$$y = f(x, t)$$



Animation from CurvusPro



“Explicit” Surface in 3D

Mapping

$$F: \mathbb{R}^2 \rightarrow \mathbb{R}$$

Definition:

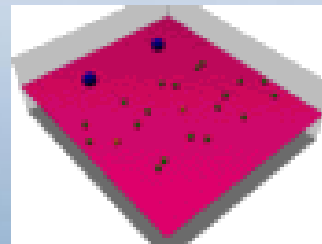
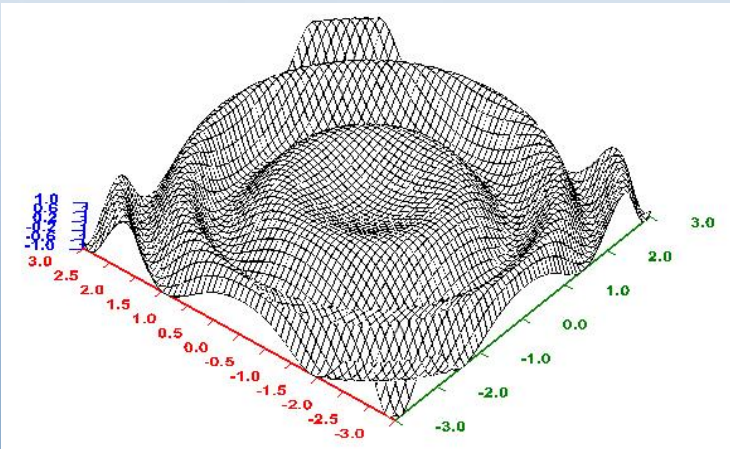
$$z = f(x, y)$$

+ time t

$$F: \mathbb{R}^3 \rightarrow \mathbb{R}$$

Definition:

$$z = f(x, y, t)$$



Animation from CurvusPro

Image from HyperFun

Other terms: relief surface, height field, depth field, 2.5D



Volume – “Explicit” Hypersurface in 4D

Mapping $F: \mathbb{R}^3 \rightarrow \mathbb{R}$

Definition: $\lambda = f(x, y, z)$

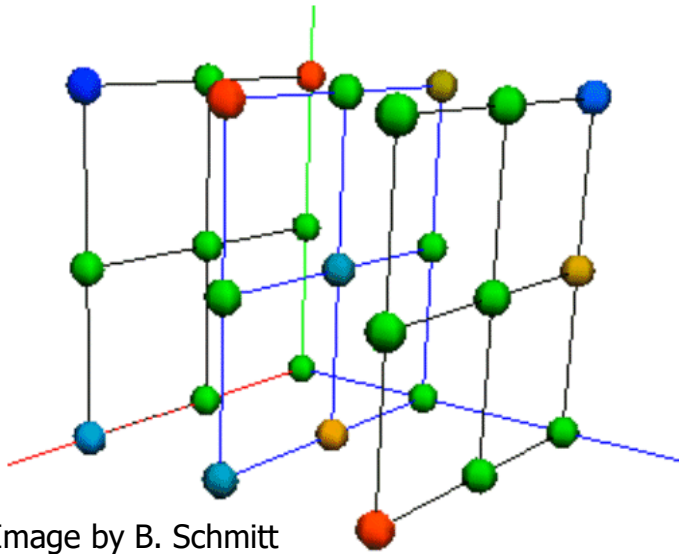


Image by B. Schmitt

Discrete scalar field: function λ
is defined in the grid nodes

Other terms: volumetric object, voxel object, 3D scalar field



Volume rendering of smoke
density function λ

Image by A. Winter



Volume Image of Head



This example shows a **volume rendered** as a **semitransparent media** with **variable density** in space.



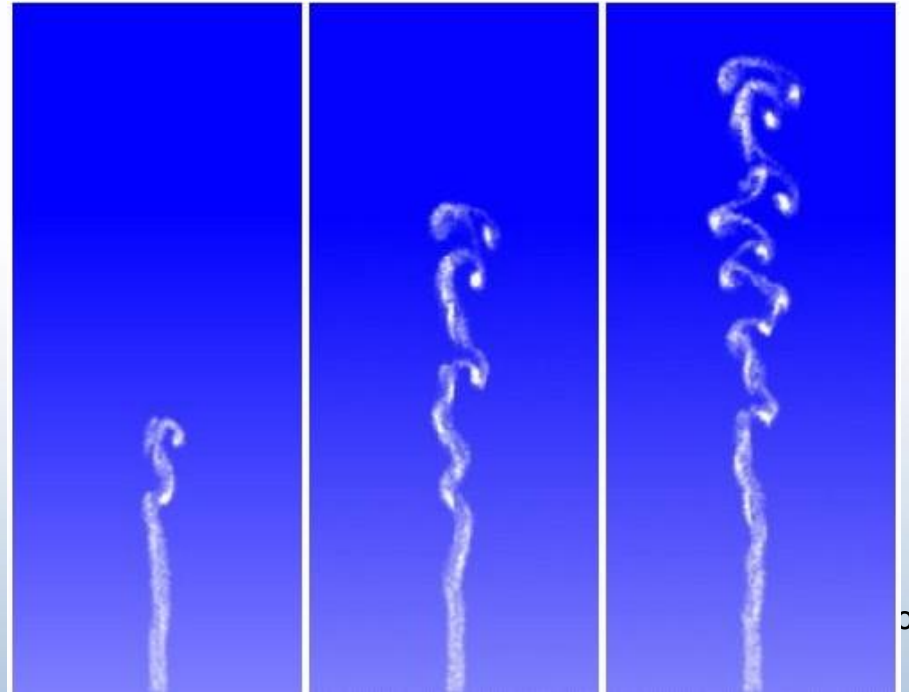
Volume - "Explicit" Hypersurface in 4D

+ time t

Mapping $F: \mathbb{R}^4 \rightarrow \mathbb{R}$

Definition:

$$\lambda = f(x, y, z, t)$$



Frames of volumetric animation - rendering of time-dependent smoke density function λ



2D Parametric Curve

Mapping $F: \mathbb{R} \rightarrow \mathbb{R}^2$

Definition:

$$\mathbf{x} = \mathbf{x}(u)$$

$$\mathbf{y} = \mathbf{y}(u)$$

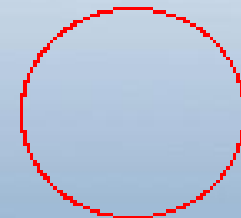
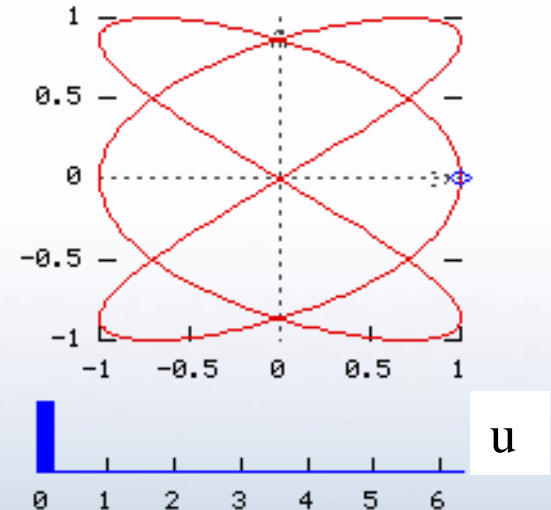
+ time t

Mapping $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

Definition:

$$\mathbf{x} = \mathbf{x}(u, t)$$

$$\mathbf{y} = \mathbf{y}(u, t)$$



Animations from WIMS
at wims.univ-mrs.fr



3D Parametric Curve

Mapping $F: \mathbb{R} \rightarrow \mathbb{R}^3$

$$\mathbf{x} = \mathbf{x}(u)$$

$$\mathbf{y} = \mathbf{y}(u)$$

$$\mathbf{z} = \mathbf{z}(u)$$



+ time t

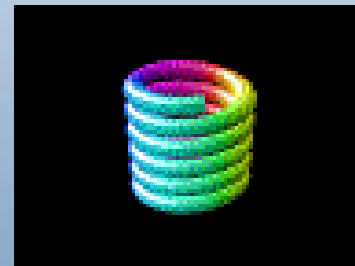
Mapping $F: \mathbb{R}^2 \rightarrow \mathbb{R}^3$

Definition:

$$\mathbf{x} = \mathbf{x}(u, t)$$

$$\mathbf{y} = \mathbf{y}(u, t)$$

$$\mathbf{z} = \mathbf{z}(u, t)$$





Parametric curve example

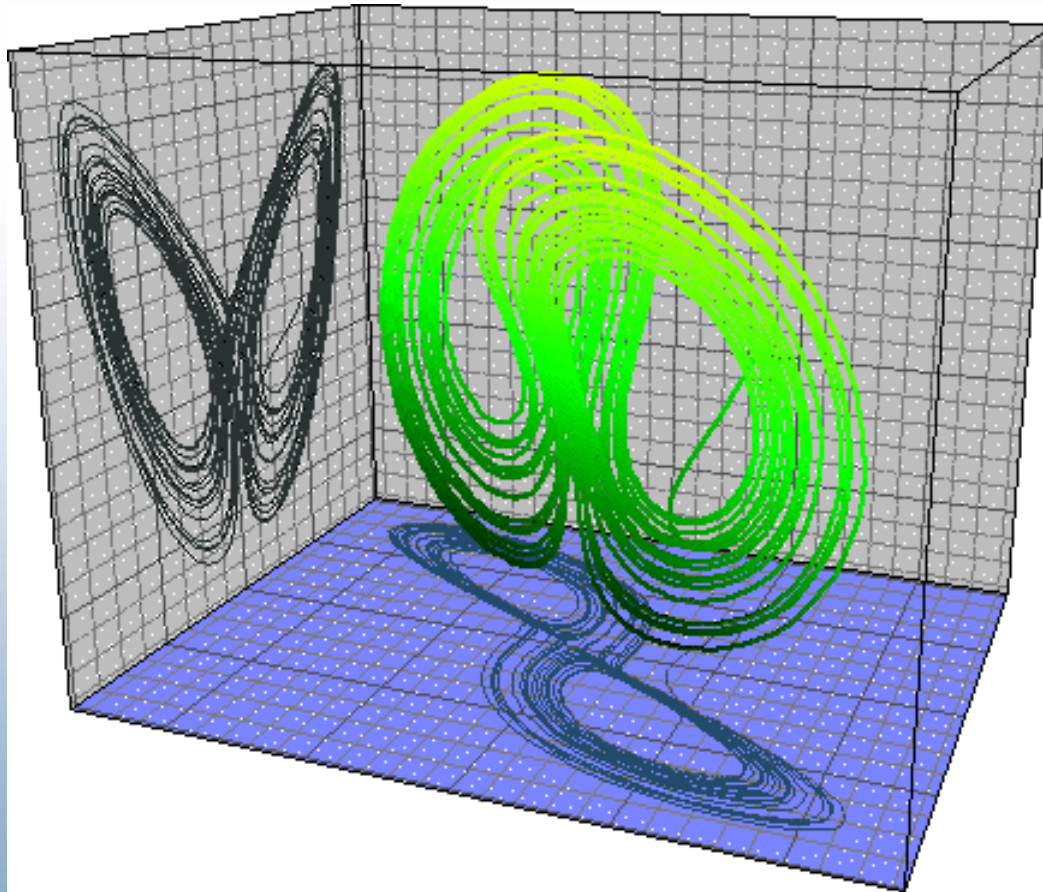


Image from CurvusPro



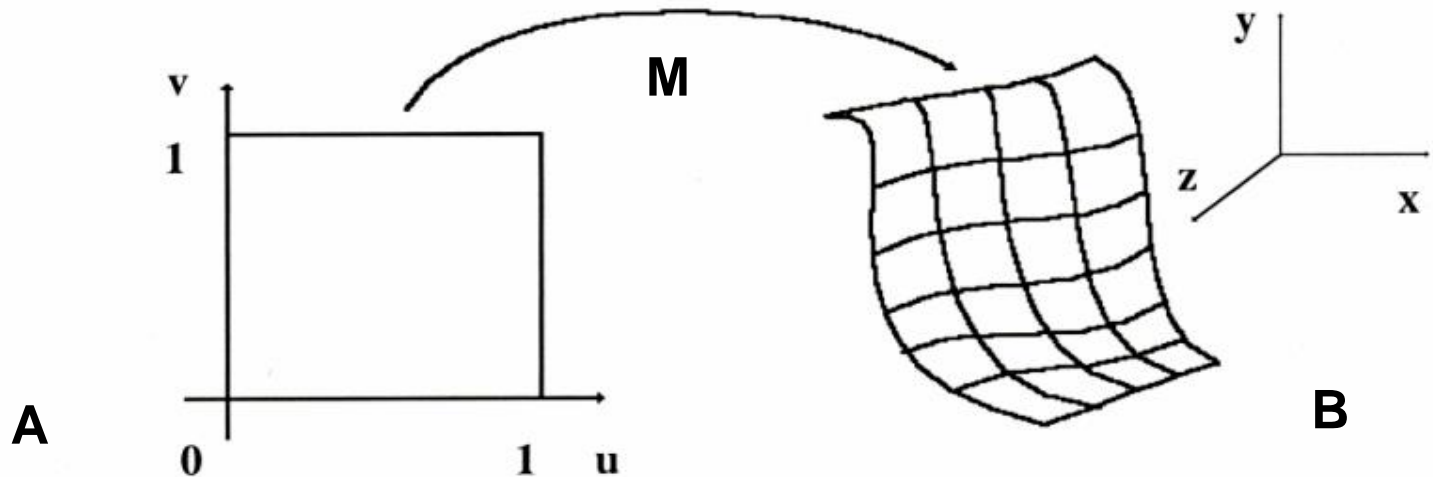
Parametric Surface

Mapping $F: E^2 \rightarrow E^3$

Model:

Surface

$$\mathbf{M}: \begin{aligned} x &= x(u, v) \\ y &= y(u, v) \\ z &= z(u, v) \end{aligned}$$





Parametric spiral surface

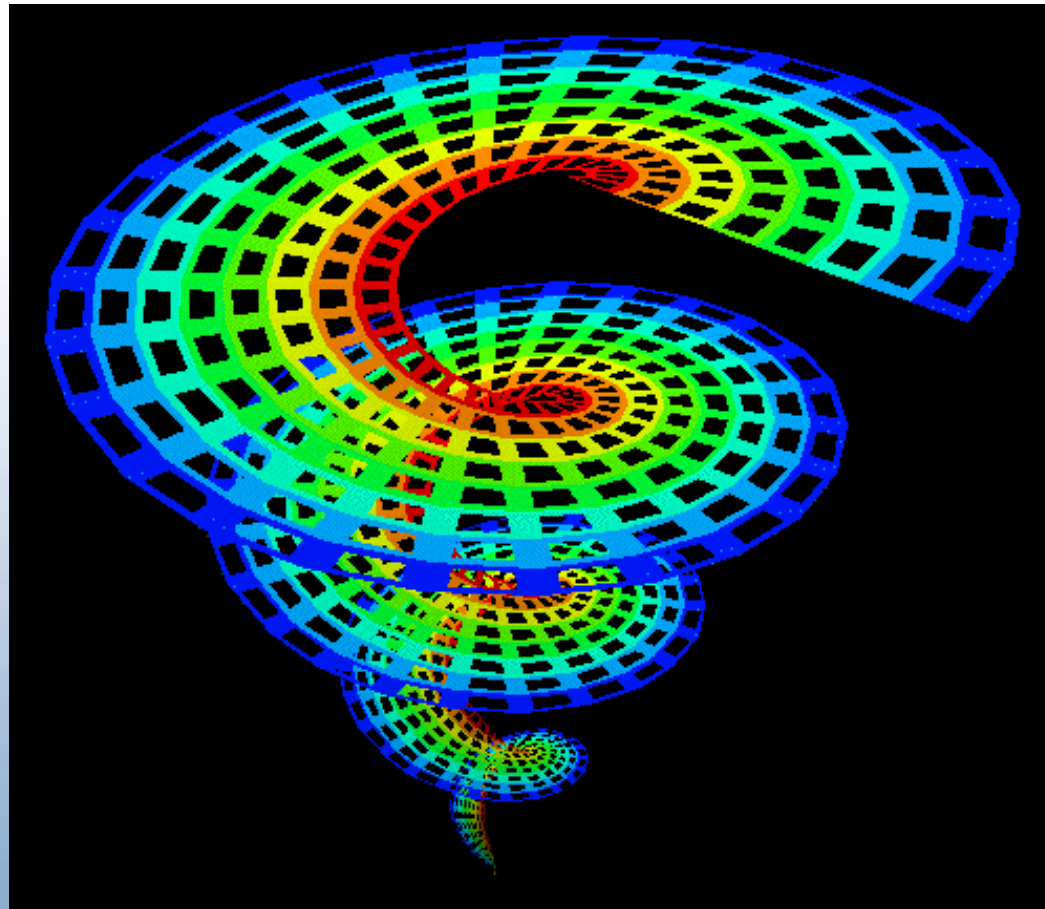


Image from CurvusPro



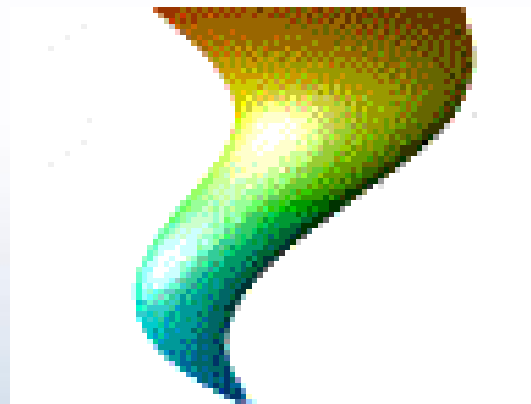
+ time T

Mapping $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

Definition: $\mathbf{x} = \mathbf{x}(\mathbf{u}, \mathbf{v}, \mathbf{t})$

$$\mathbf{y} = \mathbf{y}(\mathbf{u}, \mathbf{v}, \mathbf{t})$$

$$\mathbf{z} = \mathbf{z}(\mathbf{u}, \mathbf{v}, \mathbf{t})$$



Animation by David Parker



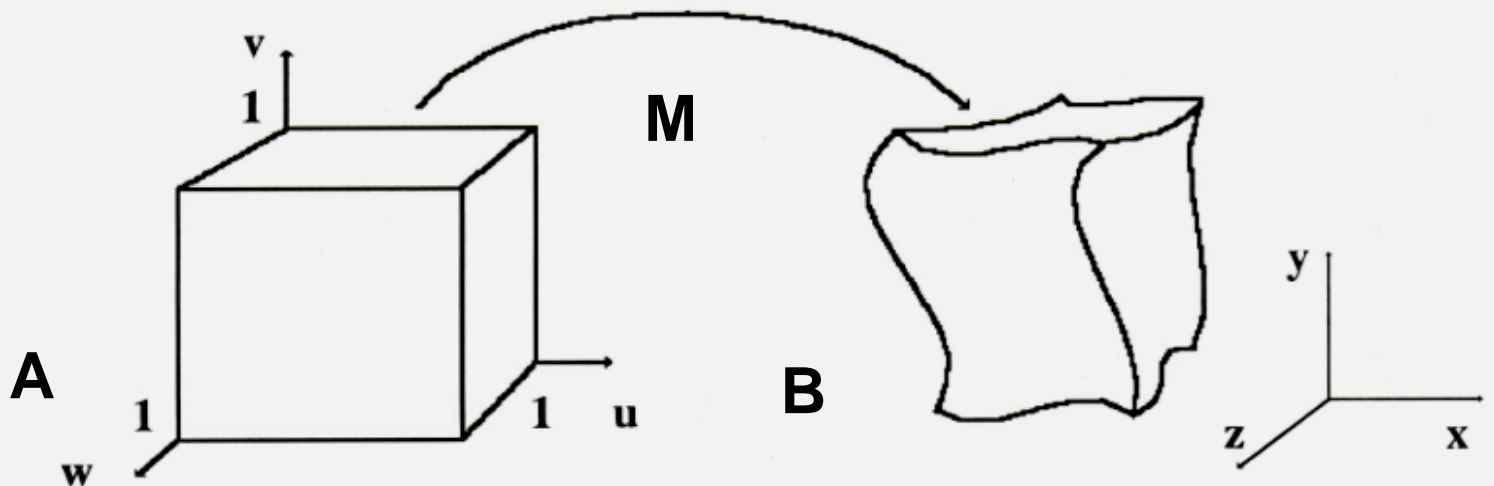
Parametric Solid

Mapping $F: E^3 \rightarrow E^3$

Model:

Solid

$$\begin{aligned} \mathbf{M}: \\ x &= x(u, v, w) \\ y &= y(u, v, w) \\ z &= z(u, v, w) \end{aligned}$$





Parametric Coons Solids

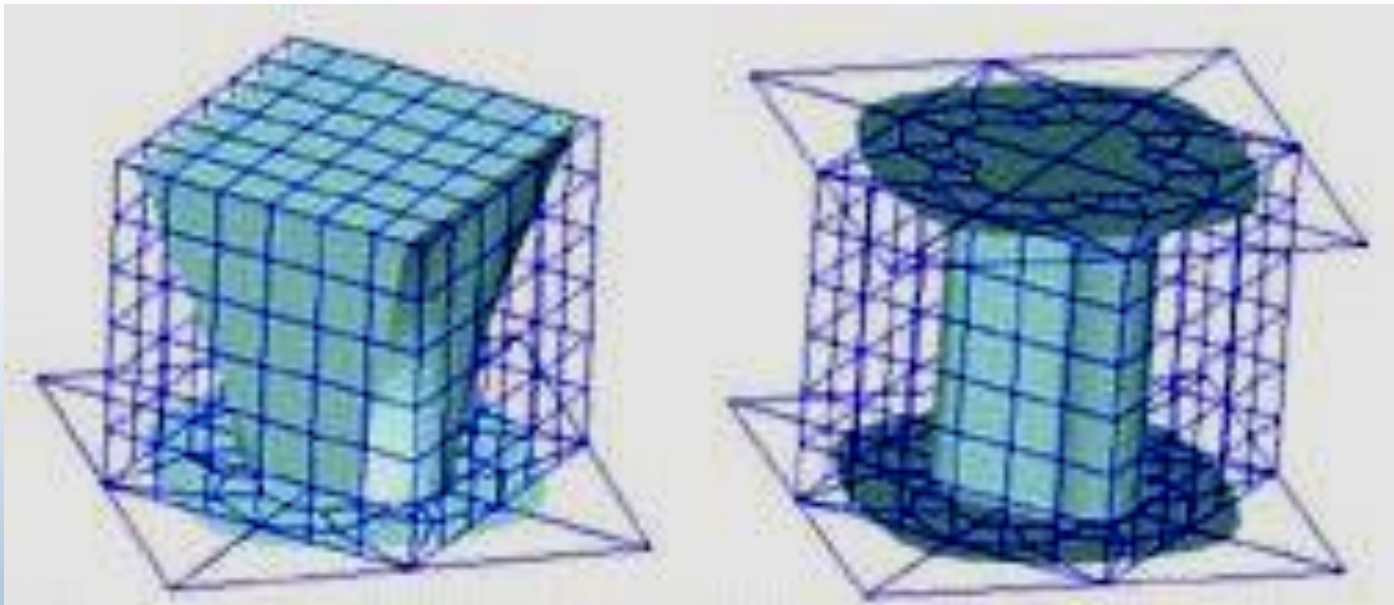
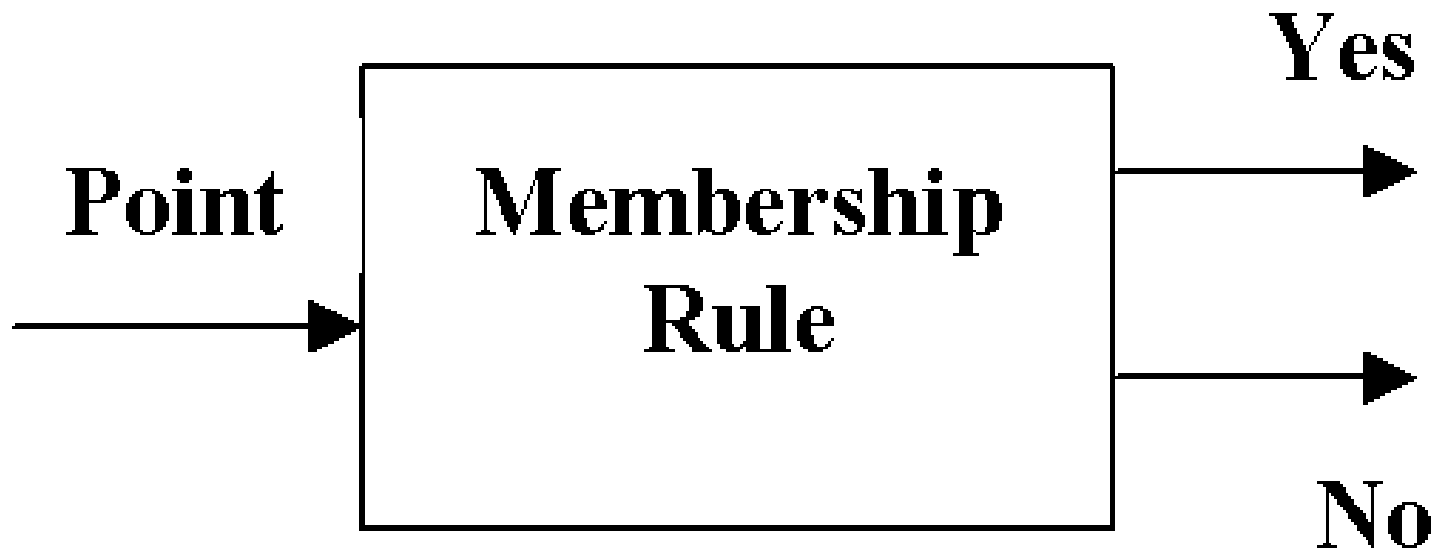


Image by S. Czanner and R. Durikovic, University of Aizu



Point Membership Rule



“Implicit” form



“Implicit” Form

$f(x_1, x_2, \dots, x_n)$ -
continuous real
function of n
variables.

Implicit objects in
 nD space:

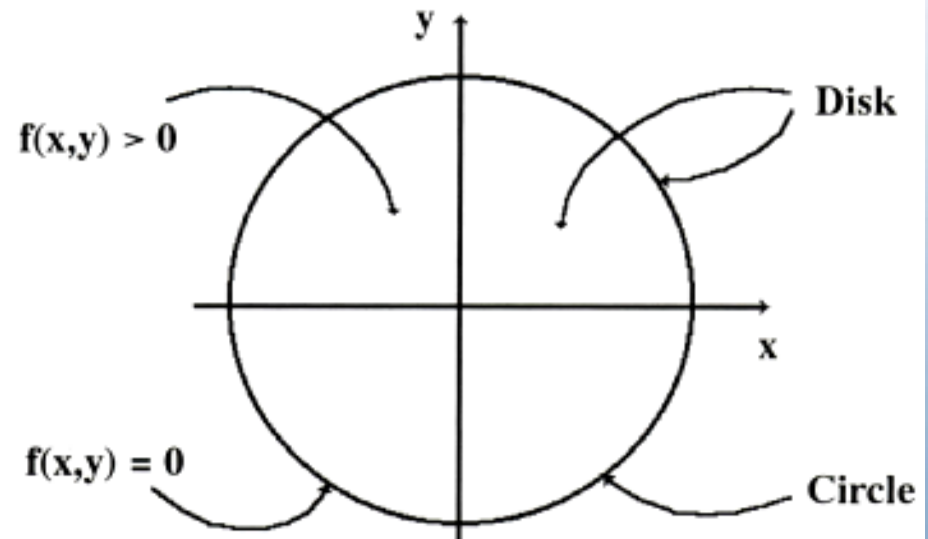
Solid ($k=n$):

$$f(x_1, x_2, \dots, x_n) \geq 0$$

Others ($k < n$):

$$f(x_1, x_2, \dots, x_n) = 0$$

	$f(x, y) = R^2 - x^2 - y^2$
Disk ($k=2$)	$f(x, y) \geq 0$
Circle ($k=1$)	$f(x, y) = 0$





“Implicit” Curve in 2D

$$f(x,y)=0$$

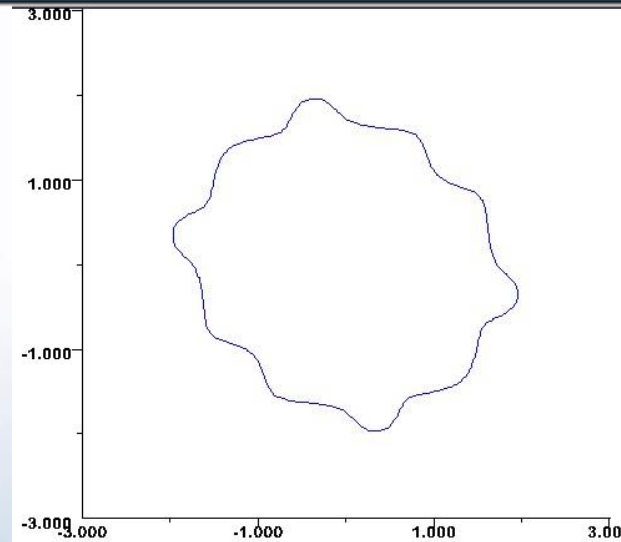


Image from HyperFun

+ time t

$$f(x,y,t) = 0$$



Animation from HyperFun

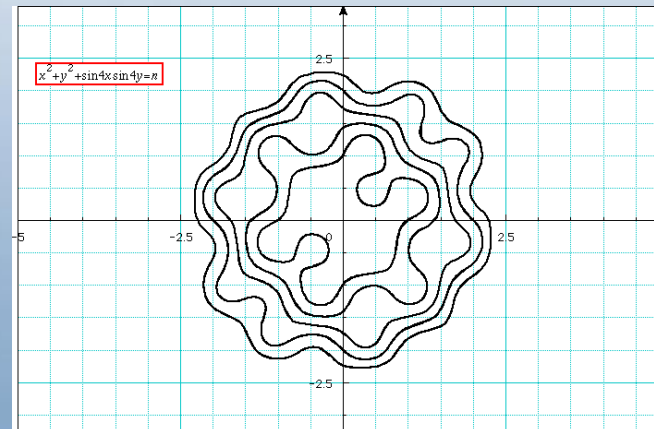


Image from CurvusPro



Isosurface or “Implicit” Surface

$$\xi = f(\mathbf{x}, \mathbf{y}, \mathbf{z})$$

is a **function of three variables** and a surface

$$\xi = 0 \quad \text{or} \quad f(\mathbf{x}, \mathbf{y}, \mathbf{z}) = 0$$

is an **iso-valued surface** (*isosurface*) or an “implicit” surface)

Sphere: $\mathbf{R}^2 - \mathbf{x}^2 - \mathbf{y}^2 - \mathbf{z}^2 = 0$



Implicit Surfaces and Solids

A set of points in 3D space with

$$f(x, y, z) = 0$$

is called an implicit surface

A 3D solid is defined as

$$f(x, y, z) \geq 0$$

with the implicit surface as its boundary.



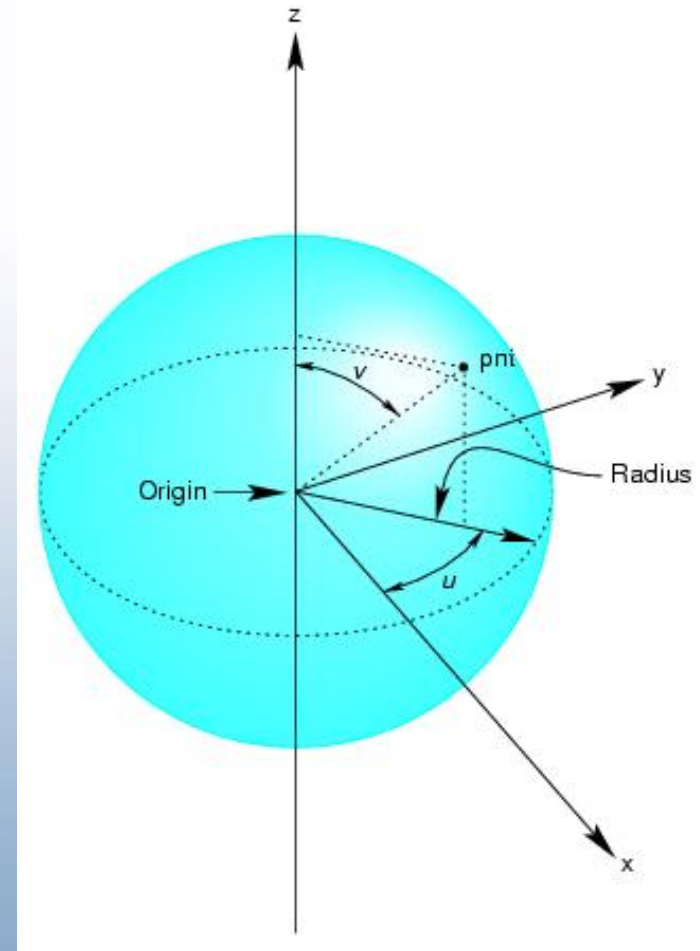
Sphere and Solid Ball

Sphere surface:

$$R^2 - x^2 - y^2 - z^2 = 0$$

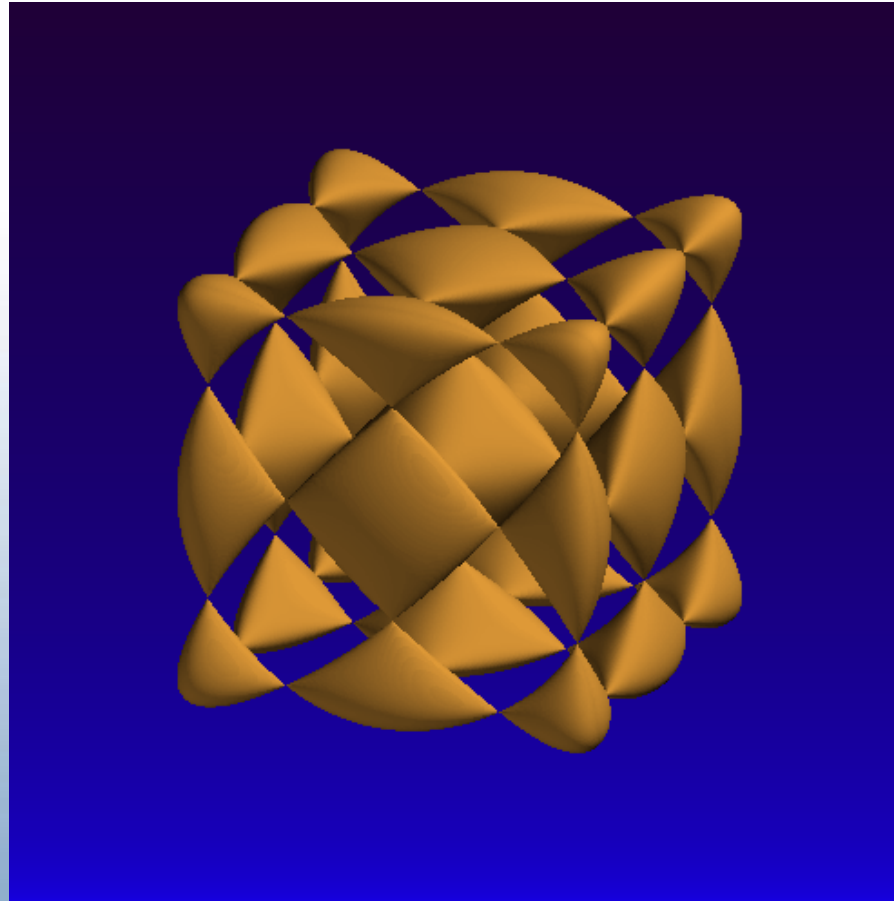
Solid ball:

$$R^2 - x^2 - y^2 - z^2 \geq 0$$





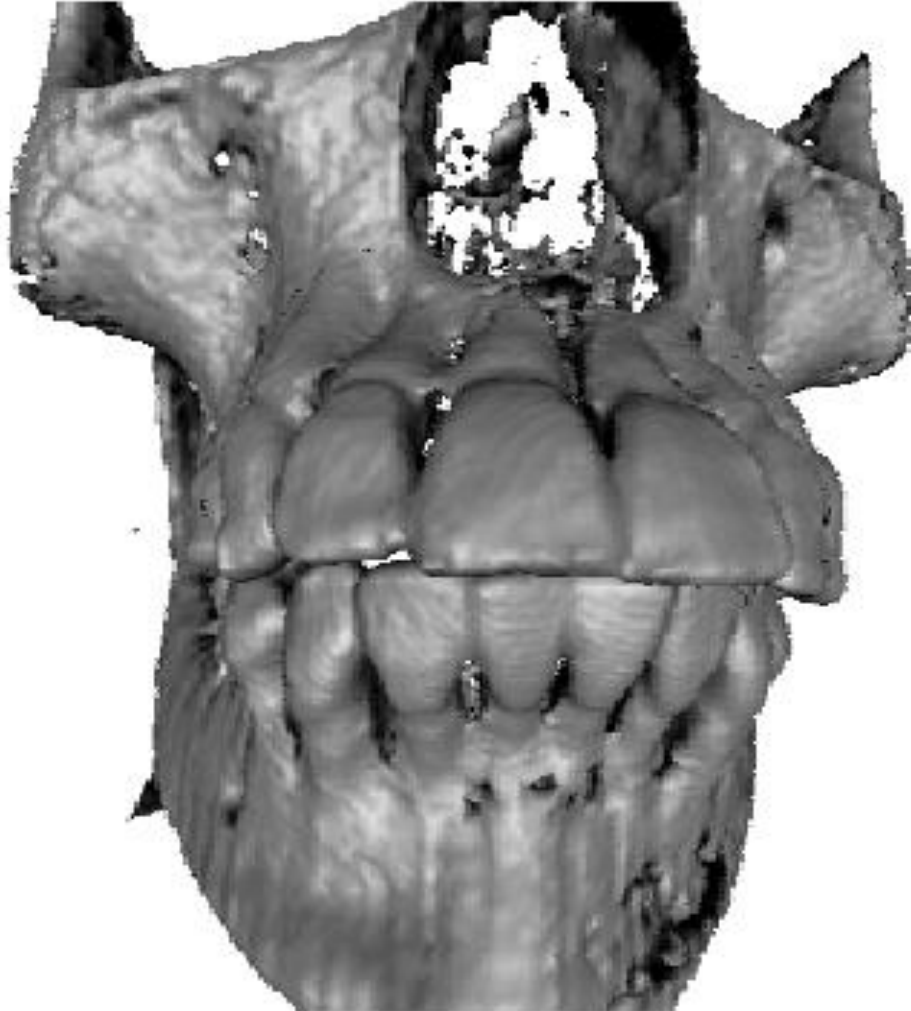
Chebyshev Polynomial



Complex isosurface defined by equation $f(x,y,z)=0$



Teeth Isosurface

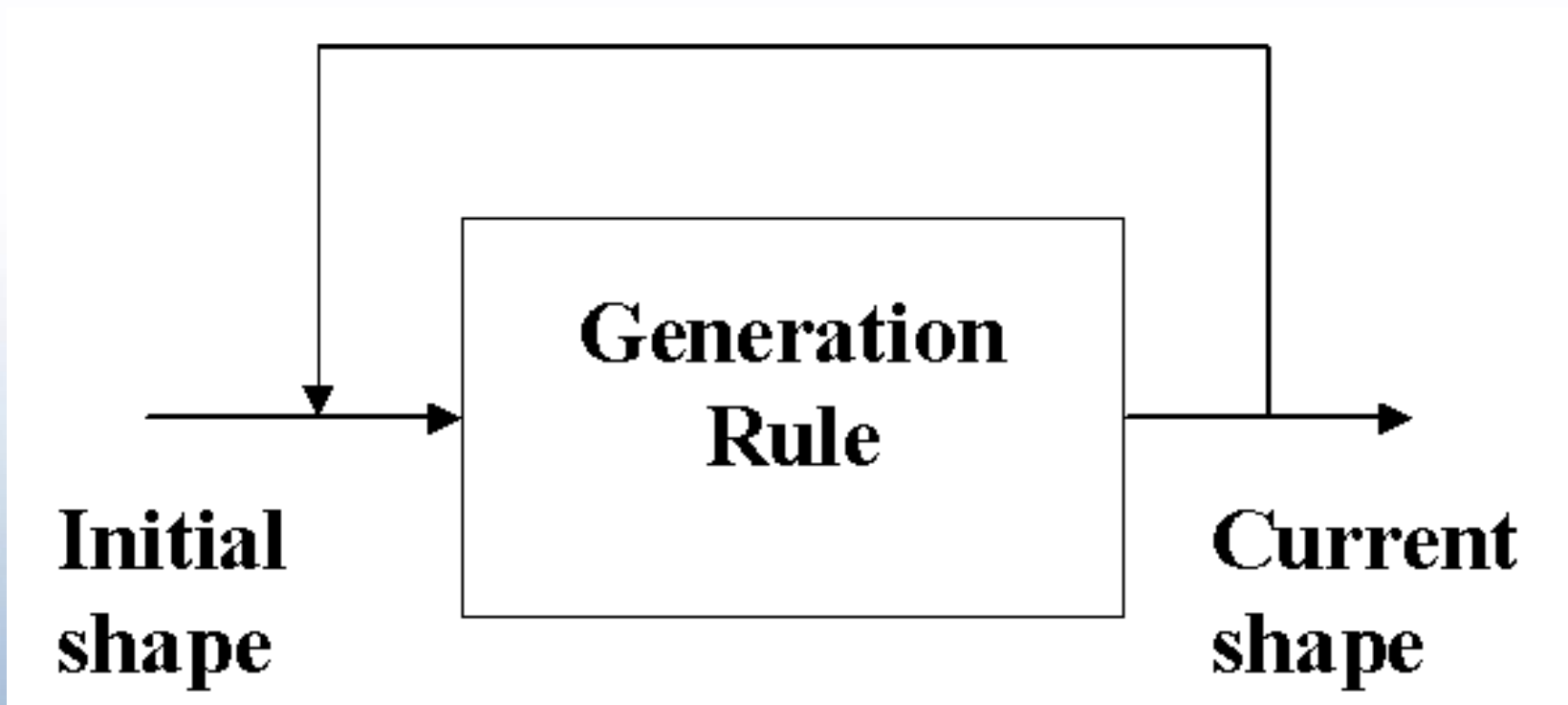


Isosurface defined by
volume data
 $f(x_i, y_j, z_k) = c$

Image by D. Fang et al.,
University of California, Davis
Dataset of Siemens Medical Systems



Generation Rule



A rule can be specified to generate a shape in a recursive manner (fractals, L-systems, other procedural models)



Fractals

Model:
iterative functions $p' = f(p)$
in 2D or 3D space.

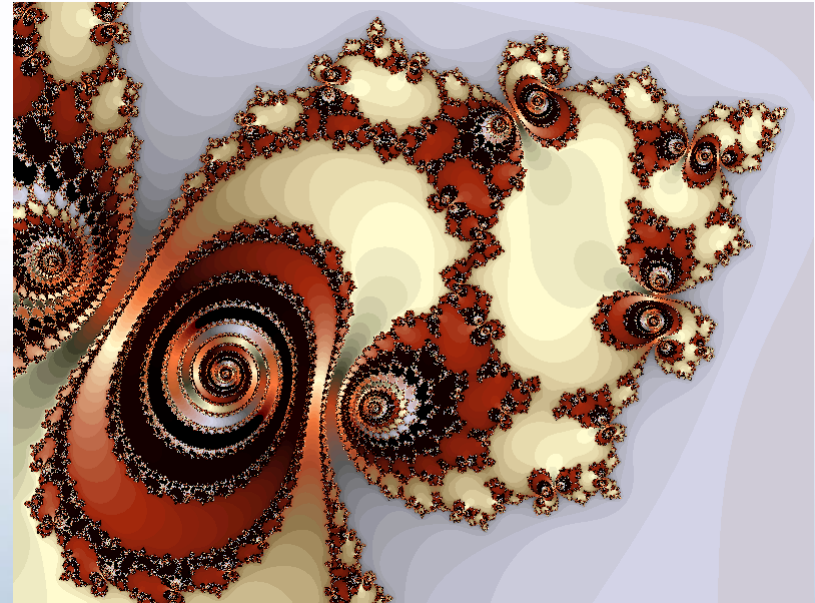
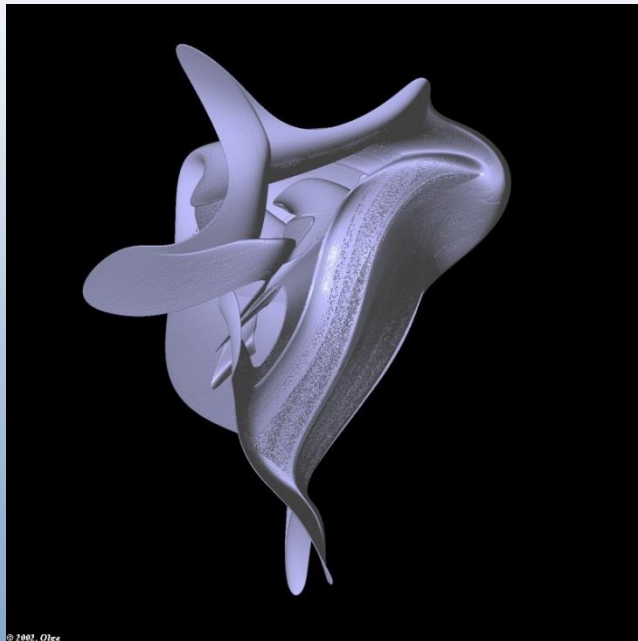


Image by Linda Allison

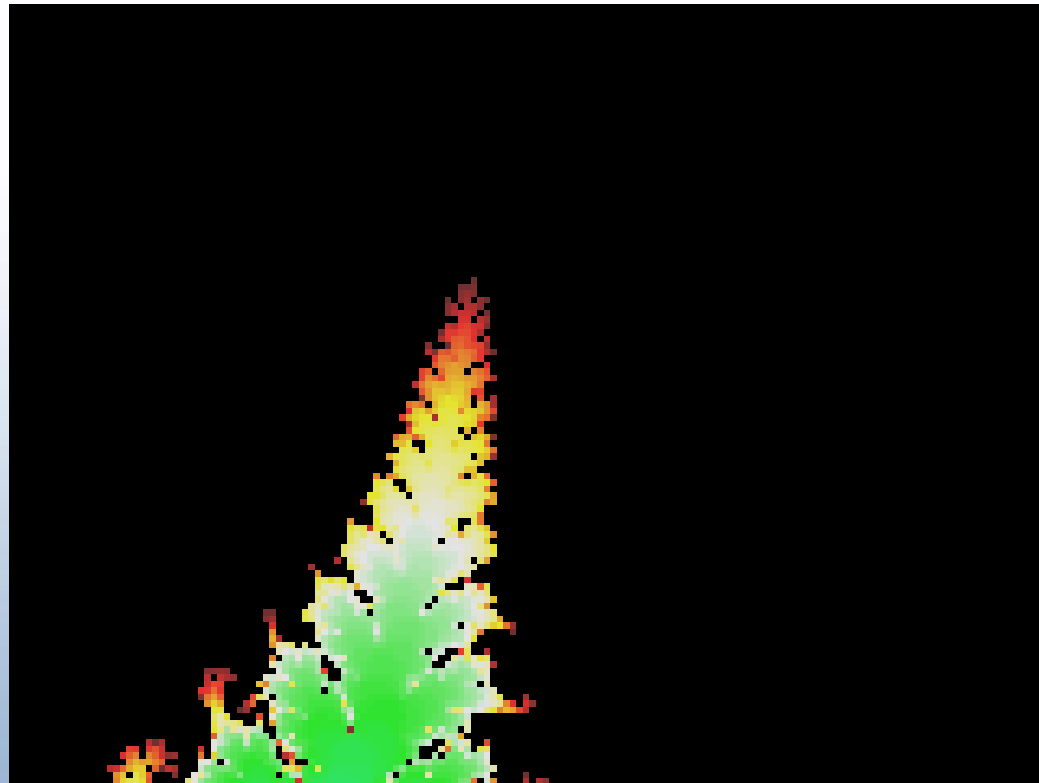
Image "Thick ballerina" by Olga

<http://www.eclectasy.com/Fractal-Explorer/>



Fractal animation

+ time t
 $p' = f(p, t)$



Animation from Filmer
by Julian Haight



L - systems

Model: grammar

Example:

1) Axiom X

2) Rules

$X \rightarrow F-[[X]+X]+F[+FX]-X$

$F \rightarrow FF$

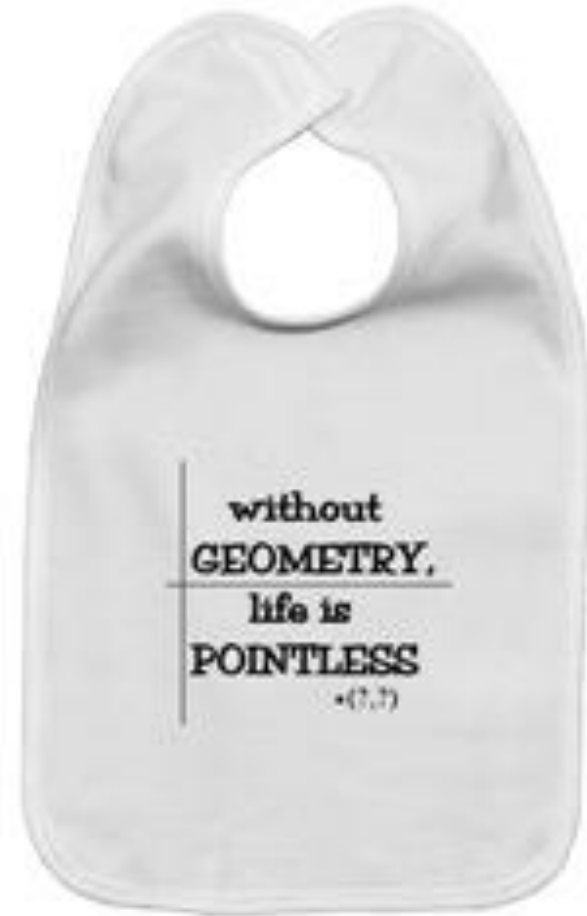




Words of wisdom

*"Geometry is the
mathematical
science of shape"*

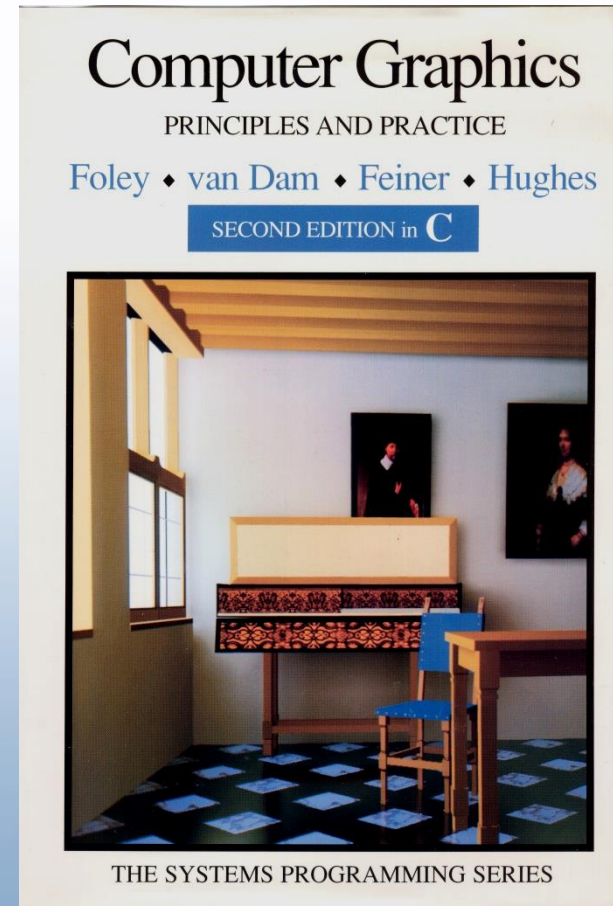
*"Without geometry,
life is pointless"*





References

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References

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- Carl Vilbrandt, Computer Aided Design's eXtended Dimensions
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